



Recall from Tuesday last week
A is an nxn matrix.

$$A\vec{x} = \lambda\vec{x}, \quad \vec{x} \neq \vec{0}$$

 $\lambda \leftarrow eigenvalue$
 $\vec{x} \leftarrow eigenvectos$
You can find the eigenvalues
of A by solving the
of A by solving the
characteristic polynomial
 $det(A - \lambda In) = 0$
 $E_{\lambda}(A) = \{\vec{x} \mid A\vec{x} = \lambda\vec{x}\}$
Eigenspace for λ

Facts/Defs Let A be an nxn matrix. Let X be eigenvalue of A. () The eigenspace $E_{\lambda}(A)$ is a subspace of IR". (2) The dimension of E₁(A) is called the geometric multiplicity of λ . (3) The algebraic multiplicity of A is the multiplicity of A as a root of the characteristic polynomial of A. $\left(\begin{array}{c} \text{geometric multiplicity}\\ \text{ot } \lambda\end{array}\right) \leq \left(\begin{array}{c} \text{algebraic}\\ \text{multiplicity}\\ \text{ot } \lambda\end{array}\right)$ (4)

Example we started last time $A = \begin{pmatrix} 0 & 0 & -2 \\ 1 & 2 & 1 \\ 1 & 0 & 3 \end{pmatrix}$ characteristic polynomial: det $(A - \lambda I_3) = -(\lambda - 2)(\lambda - 1)$ algebraic eigenvalue 2 - > = [- 入 = 2 /

We also found a basis for $E_{1}(A) = \{ X \mid AX = I \cdot X \}$ it was $\begin{pmatrix} -2 \\ 1 \end{pmatrix}$. Thus, the germetric multiplicity of $\lambda = 1$ is $dim(E_{A}) = [$ I vector in basis Let's now find a basis for $E_z(A) = \underbrace{\exists \forall A \\ x = 2 \\ x \end{bmatrix}$ $A = 2 \times -$ Want to solve So need to solve

$$\begin{pmatrix} 0 & 0 & -2 \\ 1 & 2 & 1 \\ 1 & 0 & 3 \end{pmatrix} \begin{pmatrix} \alpha \\ b \\ c \end{pmatrix} = 2 \begin{pmatrix} \alpha \\ b \\ c \end{pmatrix} = -Ax = 2x$$
$$\begin{pmatrix} -2c \\ \alpha + 2b + c \\ \alpha + 3c \end{pmatrix} = \begin{pmatrix} 2\alpha \\ 2b \\ 2c \end{pmatrix}$$
$$\begin{pmatrix} -2\alpha & -2c \\ \alpha + c \\ \alpha + c \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

This gives

$$\begin{array}{ccc} -2a & -2c = 0 \\ a & +c = 0 \\ a & +c = 0 \end{array}$$

$$\begin{pmatrix} -2 & 0 & -2 & | & 0 \\ | & 0 & | & | & 0 \\ | & 0 & | & | & 0 \end{pmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{pmatrix} | & 0 & | & 0 \\ -2 & 0 & -2 & | & 0 \\ | & 0 & | & | & 0 \end{pmatrix}$$

$$\begin{array}{c} ZR_1 + R_2 \rightarrow R_2 \\ \hline R_1 + R_3 \rightarrow R_3 \end{pmatrix} \begin{pmatrix} | & 0 & | & | & 0 \\ 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix}$$

This gives:

$$\begin{array}{cccc}
\alpha & +c &= 0 \\
& 0 &= 0 \\
& 0 &= 0
\end{array}$$

leading: a free: c, b

Solution: b = t c = ua = -c = -u

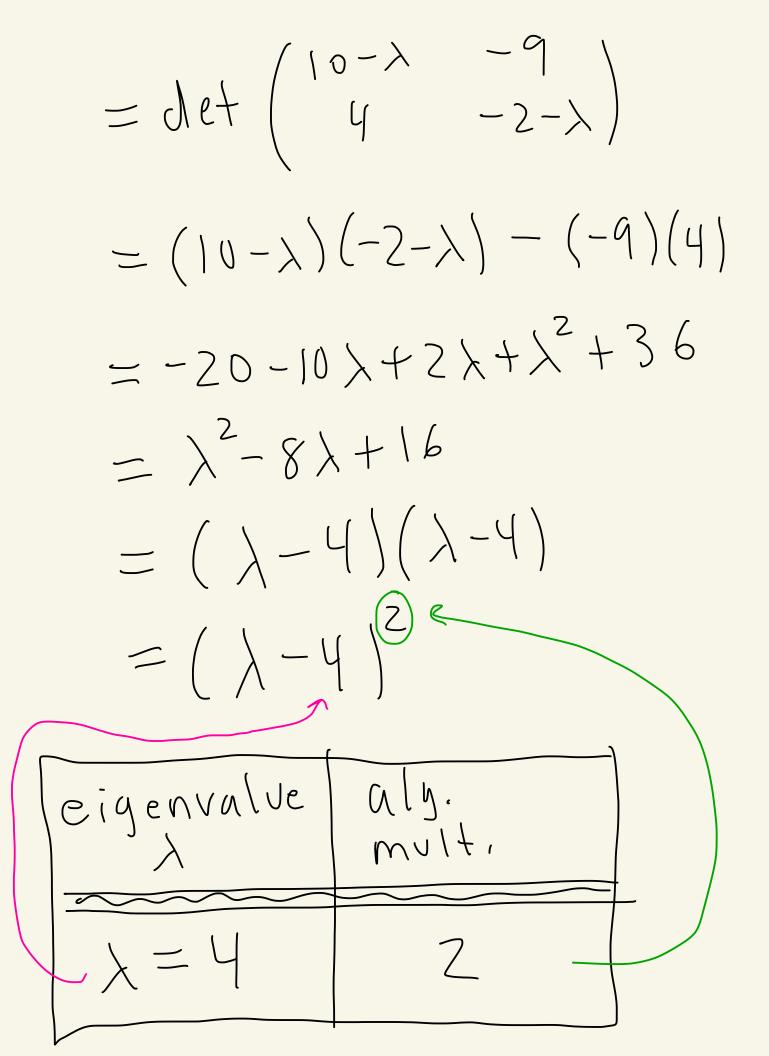
Thus, if x solves Ax = 2x then

$$\vec{x} = \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} -u \\ t \\ u \end{pmatrix}$$
$$= \begin{pmatrix} -u \\ 0 \\ u \end{pmatrix} + \begin{pmatrix} 0 \\ t \\ 0 \end{pmatrix}$$
$$= u \begin{pmatrix} -i \\ 0 \\ 1 \end{pmatrix} + t \begin{pmatrix} 0 \\ i \\ 0 \end{pmatrix}$$
So all solutions of $A\vec{x} = 2\vec{x}$ are linear combinations of $\begin{pmatrix} -i \\ 0 \\ 1 \end{pmatrix}$ and $\begin{pmatrix} 0 \\ i \\ 0 \end{pmatrix}$.
Thus, $\begin{pmatrix} -i \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ span the eigenspace $E_2(A)$.
You can verify that $\begin{pmatrix} -i \\ 0 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$.

Thus,
$$\left(\frac{1}{2}\right)_{1}\left(\frac{1}{2}\right)_{1}\left(\frac{1}{2}\right)_{1}$$
 is a basic for
 $E_{2}(A)_{1}$, So, $\lambda = 2$ has
geometric multiplicity
 $\dim(E_{2}(A)) = 2$.
Summary table for A:

| Eigenvalue 1 | alg.mult. of X | basis for EX(A) | geometric muilt, |
|------------------|-------------------|--|---------------------|
| $\sum_{i=1}^{n}$ | | $\begin{pmatrix} -2 \\ l \\ l \end{pmatrix}$ | |
| $\lambda = Z$ | Z | $ \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} $ | Z |

$$\begin{aligned} \overline{Ex:} & (HW \ 8 \ \# 1(b)) \\ \text{Let } A = \begin{pmatrix} 10 & -9 \\ 4 & -2 \end{pmatrix} \\ \\ \overline{Find } \text{ the eigenvalues, basis for} \\ each eigenvalue, alg. & geom. mult. \\ of each eigenvalue. \\ \\ \\ \hline Eigenvalue \ \text{time!} \end{pmatrix} \qquad \begin{array}{l} \text{characteristic} \\ \text{poly.} \\ \\ \\ \text{det}(A - \lambda I_z) = \\ \\ = det\left(\begin{pmatrix} 10 & -9 \\ 4 & -2 \end{pmatrix} - \lambda \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}\right) \\ \\ = det\left(\begin{pmatrix} 10 & -9 \\ 4 & -2 \end{pmatrix} + \begin{pmatrix} -\lambda & 0 \\ 0 & -\lambda \end{pmatrix}\right) \end{aligned}$$



Let's get a basis for

$$E_{4}(A) = \{ \vec{x} \mid A \vec{x} = 4 \vec{x} \}$$

Need to solve $A \vec{x} = 4 \vec{x}$.
Let's solve!
 $\begin{pmatrix} 10 & -9 \\ 4 & -2 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = 4 \begin{pmatrix} a \\ b \end{pmatrix} \bigstar \vec{x} = 4 \vec{x}$.
 $\begin{pmatrix} 10a - 9b \\ 4a - 2b \end{pmatrix} = \begin{pmatrix} 4a \\ 4b \end{pmatrix}$
 $\begin{pmatrix} 6a - 9b \\ 4a - 6b \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$
This gives:
 $6a - 9b = 0$

Solving:

$$\begin{pmatrix} 6 & -9 & 0 \\ 4 & -6 & 0 \end{pmatrix} \xrightarrow{\frac{1}{6}R_1 \to R_1} \begin{pmatrix} 1 & -\frac{3}{2} & 0 \\ 4 & -6 & 0 \end{pmatrix}$$

 $-\frac{4R_1 + R_2 \to R_2}{2} \begin{pmatrix} 1 & -\frac{3}{2} & 0 \\ 0 & 0 & 0 \end{pmatrix}$

So we get:

$$\alpha - \frac{3}{2}b = 0$$
 leading: α
 $0 = 0$ free: b

Solutions:

$$b = t$$

 $a = \frac{3}{2}b = \frac{3}{2}t$

Thus if \vec{x} solves $A\vec{x} = 4\vec{x}$ then $\vec{x} = \begin{pmatrix} G \\ B \end{pmatrix} = \begin{pmatrix} 3/2 & t \\ t \end{pmatrix} = t \begin{pmatrix} 3/2 \\ l \end{pmatrix}$

Thus, a basis for Ey(A) is $\begin{pmatrix} 3/2 \\ 1 \end{pmatrix}$. Thus, $\lambda = 4$ has geometric multiplicity $dim(E_{Y}(A)) = 1$ Summary table for A Geometric basis for 919. eigenvulve mult. $E_{\lambda}(A)$ mult. of λ of X λ $\begin{pmatrix} 3/2 \\ 1 \end{pmatrix}$ $\lambda = 4$